

# One Parameter Semigroups in Two Complex Variables

---

Michael R. Pilla

October 8, 2022

Midwestern Workshop on Asymptotic Analysis; Purdue University, Fort Wayne

# Preliminary Definitions

1. A linear fractional map (aka Mobius transformation) is a complex map given by

$$\frac{az + b}{cz + d}$$

where  $ad - bc \neq 0$ .

# Preliminary Definitions

1. A linear fractional map (aka Mobius transformation) is a complex map given by

$$\frac{az + b}{cz + d}$$

where  $ad - bc \neq 0$ .

2. The unit ball in  $\mathbb{C}^N$  is given by

$$\mathbb{B}_N = \{z \in \mathbb{C}^N \mid |z| < 1\}.$$

## Preliminary Definitions

$$\mathcal{T} = \{\phi : \mathbb{B}_N \rightarrow \mathbb{B}_N \mid \phi \text{ nonconstant, analytic, not an automorphism}\}$$

## Preliminary Definitions

$$\mathcal{T} = \{\phi : \mathbb{B}_N \rightarrow \mathbb{B}_N \mid \phi \text{ nonconstant, analytic, not an automorphism}\}$$

For  $\phi \in \mathcal{T}$ , it is clear that the set of iterates  $\{\phi_n\}$  under composition for  $n = 0, 1, 2, \dots$ , defines a discrete semigroup.

# Preliminary Definitions

$$\mathcal{T} = \{\phi : \mathbb{B}_N \rightarrow \mathbb{B}_N \mid \phi \text{ nonconstant, analytic, not an automorphism}\}$$

For  $\phi \in \mathcal{T}$ , it is clear that the set of iterates  $\{\phi_n\}$  under composition for  $n = 0, 1, 2, \dots$ , defines a discrete semigroup.

A **one parameter semigroup** for a monoid  $(S, *)$  is a map  $\phi : [0, \infty) \rightarrow S$ , such that

1.  $\phi(0) = I$ .
2.  $\phi(s + t) = \phi(s) * \phi(t)$ .

## One Way to Classify Self Maps of the Disk.

For an analytic self-map  $\phi$  of the disk, either  $\phi$  has a fixed point in the disk or else it doesn't. If  $\phi$  has no fixed point in the disk, then there is a unique fixed point  $\alpha$  on the boundary with  $d(\alpha) \leq 1$ .

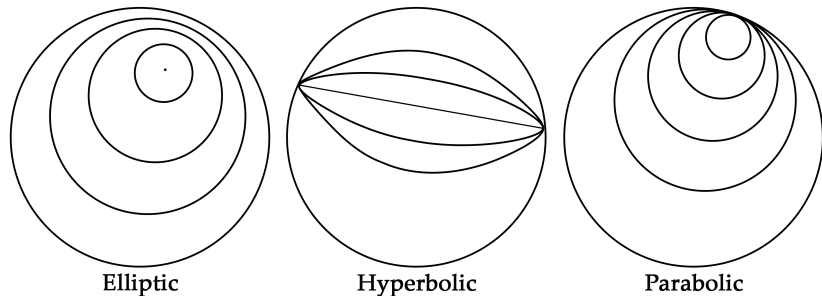
Let  $\phi(\alpha) = \alpha$ . We classify as follows:

1. Elliptic:  $\alpha \in \mathbb{D}$ .
2. Hyperbolic:  $|\alpha| = 1$  and  $d(\alpha) < 1$ .
3. Parabolic:  $|\alpha| = 1$  and  $d(\alpha) = 1$ .

where  $d(\alpha)$  is the boundary dilation coefficient.

# The Fixed-Point Behavior is Important

The one-parameter semigroup  $\{\phi_t\}$  depends on its fixed point behavior.



**Figure 1:** Automorphisms of the Disk



## Another Way to Classify Self Maps of the Disk: Part I

(Cowen 1981) Under very general conditions, for an analytic map  $\phi : \mathbb{D} \rightarrow \mathbb{D}$ , there is a domain  $\Omega$ , either the plane or half-plane, a mapping  $\sigma$  of  $\mathbb{D}$  into  $\Omega$  and a 'model' linear fractional automorphism  $\Phi$  of  $\Omega$  such that

$$\sigma \circ \phi = \Phi \circ \sigma$$

We have the following commutative diagram

$$\begin{array}{ccc} \mathbb{D} & \xrightarrow{\phi} & \mathbb{D} \\ \downarrow \sigma & & \downarrow \sigma \\ \Omega & \xrightarrow{\Phi} & \Omega \end{array}$$

## Another Way to Classify Self Maps of the Disk: Part I

(Cowen 1981) Under very general conditions, for an analytic map  $\phi : \mathbb{D} \rightarrow \mathbb{D}$ , there is a domain  $\Omega$ , either the plane or half-plane, a mapping  $\sigma$  of  $\mathbb{D}$  into  $\Omega$  and a 'model' linear fractional automorphism  $\Phi$  of  $\Omega$  such that

$$\sigma \circ \phi = \Phi \circ \sigma \rightarrow \sigma \circ \phi_n = \Phi_n \circ \sigma.$$

We have the following commutative diagram

$$\begin{array}{ccc} \mathbb{D} & \xrightarrow{\phi} & \mathbb{D} \\ \downarrow \sigma & & \downarrow \sigma \\ \Omega & \xrightarrow{\Phi} & \Omega \end{array}$$

## Another Way to Classify Self Maps of the Disk: Part II

After appropriate conjugation, one has the following classification:

1. (Plane/Dilation):  $\Omega = \mathbb{C}$ ,  $\sigma(\alpha) = 0$  and  $\Phi(z) = sz$  with  $0 < |s| < 1$ .
2. (Plane/Translation):  $\Omega = \mathbb{C}$ ,  $\sigma(\alpha) = \infty$  and  $\Phi(z) = z + 1$ .
3. (Halfplane/Dilation):  $\Omega = \{z \mid \Re z > 0\}$ ,  $\sigma(\alpha) = 0$  and  $\Phi(z) = sz$  with  $0 < s < 1$ .
4. (Halfplane/Translation):  $\Omega = \{z \mid \Im z > 0\}$ ,  $\sigma(\alpha) = \infty$  and  $\Phi(z) = z \pm 1$ .

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

To find  $\{\phi_t\}$ , we put  $\phi_t = \sigma^{-1} \circ \Phi_t \circ \sigma$  where  $\Phi_t(z) = \frac{1}{2^t}z$ .

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

To find  $\{\phi_t\}$ , we put  $\phi_t = \sigma^{-1} \circ \Phi_t \circ \sigma$  where  $\Phi_t(z) = \frac{1}{2^t}z$ . Thus we have

$$\phi_t(z) = \frac{1}{2^t}z + 1 - \frac{1}{2^t}.$$



## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

To find  $\{\phi_t\}$ , we put  $\phi_t = \sigma^{-1} \circ \Phi_t \circ \sigma$  where  $\Phi_t(z) = \frac{1}{2^t}z$ .

## Example in the Disk.

### Example

Let  $\phi(z) = \frac{1}{2}z + \frac{1}{2}$  be a self-map of the disk.

To conform to our model we put  $\sigma(z) = 1 - z$  and  $\Phi(z) = \frac{1}{2}z$  which gives us

$$\sigma \circ \phi(z) = 1 - \left( \frac{1}{2}z + \frac{1}{2} \right) = \frac{1}{2} - \frac{1}{2}z = \frac{1}{2}(1 - z) = \Phi \circ \sigma(z).$$

To find  $\{\phi_t\}$ , we put  $\phi_t = \sigma^{-1} \circ \Phi_t \circ \sigma$  where  $\Phi_t(z) = \frac{1}{2^t}z$ . Thus we have

$$\phi_t(z) = \frac{1}{2^t}z + 1 - \frac{1}{2^t}.$$

## Pivot to $\mathbb{B}_N$ .

Let  $\phi$  be an analytic self map of  $\mathbb{B}_N$ .

1. If  $\phi$  is a fixed point free self-map of  $\mathbb{B}_N$ , then there exists a unique point  $\alpha$  on the boundary such that the iterates of  $\phi$  converge uniformly to  $\alpha$  on compact subsets of  $\mathbb{B}_N$ . We call this the Denjoy-Wolff point. (MacCluer 1982)

## Pivot to $\mathbb{B}_N$ .

Let  $\phi$  be an analytic self map of  $\mathbb{B}_N$ .

1. If  $\phi$  is a fixed point free self-map of  $\mathbb{B}_N$ , then there exists a unique point  $\alpha$  on the boundary such that the iterates of  $\phi$  converge uniformly to  $\alpha$  on compact subsets of  $\mathbb{B}_N$ . We call this the Denjoy-Wolff point. (MacCluer 1982)
2. For the continuous semigroup  $\{\phi_t\}$ , either all iterates have a common fixed point in  $\mathbb{B}_N$  or all iterates (for  $t > 0$ ) have no fixed points in  $\mathbb{B}_N$  and share the same Denjoy-Wolff point on the boundary (Abate, 1989).

# Linear Fractional Maps in Higher Dimensions

## Definition

We say  $\phi$  is a linear fractional map in  $\mathbb{C}^N$  if

$$\phi(z) = \frac{Az + B}{\langle z, C \rangle + D}$$

where  $A$  is an  $N \times N$  matrix,  $B$  and  $C$  are column vectors in  $\mathbb{C}^N$ ,  $D \in \mathbb{C}$ , and  $\langle \cdot, \cdot \rangle$  is the standard inner product.



# One Way to Classify Self Maps of the Unit Ball

For an analytic self-map  $\phi$  of  $\mathbb{B}_N$  with Denjoy-Wolff point at  $\alpha$ , we classify as follows:

1. Elliptic:  $\alpha \in \mathbb{B}_N$ .
2. Hyperbolic:  $|\alpha| = 1$  and  $d(\alpha) < 1$ .
3. Parabolic:  $|\alpha| = 1$  and  $d(\alpha) = 1$ .

# One Way to Classify Self Maps of the Unit Ball

For an analytic self-map  $\phi$  of  $\mathbb{B}_N$  with Denjoy-Wolff point at  $\alpha$ , we classify as follows:

1. Elliptic:  $\alpha \in \mathbb{B}_N$ .
2. Hyperbolic:  $|\alpha| = 1$  and  $d(\alpha) < 1$ .
3. Parabolic:  $|\alpha| = 1$  and  $d(\alpha) = 1$ .

Infinitesimal generators associated with linear fractional self maps of  $\mathbb{B}_N$  have been characterized (Bracci, Contreras, Díaz-Madrigal, 2007).

## Another Way to Classify Self Maps of the Unit Ball

Our model theory is not adequate for  $\mathbb{B}_N$ . However, one can show that the model theory extends in  $\mathbb{B}_2$  for certain maps (Cowen, et al 2006). The domains are the whole space  $\mathbb{C}^N$ , half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > 0\}$ , and Siegel half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > |z_2|^2\}$ .

## Another Way to Classify Self Maps of the Unit Ball

Our model theory is not adequate for  $\mathbb{B}_N$ . However, one can show that the model theory extends in  $\mathbb{B}_2$  for certain maps (Cowen, et al 2006). The domains are the whole space  $\mathbb{C}^N$ , half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > 0\}$ , and Siegel half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > |z_2|^2\}$ .

Our elliptic maps admits one possible case.

## Another Way to Classify Self Maps of the Unit Ball

Our model theory is not adequate for  $\mathbb{B}_N$ . However, one can show that the model theory extends in  $\mathbb{B}_2$  for certain maps (Cowen, et al 2006). The domains are the whole space  $\mathbb{C}^N$ , half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > 0\}$ , and Siegel half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > |z_2|^2\}$ .

Our elliptic maps admits one possible case.

Our hyperbolic maps admit two.

## Another Way to Classify Self Maps of the Unit Ball

Our model theory is not adequate for  $\mathbb{B}_N$ . However, one can show that the model theory extends in  $\mathbb{B}_2$  for certain maps (Cowen, et al 2006). The domains are the whole space  $\mathbb{C}^N$ , half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > 0\}$ , and Siegel half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > |z_2|^2\}$ .

Our elliptic maps admits one possible case.

Our hyperbolic maps admit two.

Our parabolic maps admit four.

## Another Way to Classify Self Maps of the Unit Ball

Our model theory is not adequate for  $\mathbb{B}_N$ . However, one can show that the model theory extends in  $\mathbb{B}_2$  for certain maps (Cowen, et al 2006). The domains are the whole space  $\mathbb{C}^N$ , half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > 0\}$ , and Siegel half space

$\Omega = \{(z_1, z_2) \in \mathbb{C}^2 \mid \Re(z_1) > |z_2|^2\}$ .

Our elliptic maps admits one possible case.

Our hyperbolic maps admit two.

Our parabolic maps admit four.

We are *presuming* that our analytic map  $\phi$  has one of the above models.

# Linear Fractional Example

## Example

Let  $\phi(z) = \left(\frac{z_1+3}{4}, \frac{z_2}{2}\right)$ . What is the Denjoy-Wolff point?



## Linear Fractional Example

### Example

Let  $\phi(z) = \left(\frac{z_1+3}{4}, \frac{z_2}{2}\right)$ . What is the Denjoy-Wolff point? To conform to our model we put  $\sigma(z) = e_1 - z$  and  $\Phi(z) = \left(\frac{1}{4}z_1, \frac{1}{2}z_2\right)$  which gives us

$$\sigma \circ \phi(z) = \left(1 - \frac{z_1+3}{4}, -\frac{z_2}{2}\right) = \left(\frac{1}{4}(1-z_1), -\frac{1}{2}z_2\right) = \Phi \circ \sigma(z).$$

# The Associated Matrix and Jordan Canonical Form

Let  $\phi$  be an LFM, then the associated matrix is defined as

$$m_\phi = \begin{pmatrix} A & B \\ C^* & D \end{pmatrix}.$$

# The Associated Matrix and Jordan Canonical Form

Let  $\phi$  be an LFM, then the associated matrix is defined as

$$m_\phi = \begin{pmatrix} A & B \\ C^* & D \end{pmatrix}.$$

A routine calculation shows that

$$m_{\phi_1 \circ \phi_2} = m_{\phi_1} m_{\phi_2} \quad \text{and} \quad m_{\phi^{-1}} = (m_\phi)^{-1}.$$

# The Associated Matrix and Jordan Canonical Form

Let  $\phi$  be an LFM, then the associated matrix is defined as

$$m_\phi = \begin{pmatrix} A & B \\ C^* & D \end{pmatrix}.$$

A routine calculation shows that

$$m_{\phi_1 \circ \phi_2} = m_{\phi_1} m_{\phi_2} \quad \text{and} \quad m_{\phi^{-1}} = (m_\phi)^{-1}.$$

Recall that Jordan Canonical Form says we can 'factor'

$$m_\phi = S\Lambda S^{-1} \rightarrow m_{\phi^n} = (m_\phi)^n = (S\Lambda S^{-1})^n = S\Lambda^n S^{-1}.$$

where the columns of  $S$  are (generalized) eigenvectors of  $m_\phi$  and  $\Lambda$  is in Jordan form.

Showing  $\phi_{t+s} = \phi_t$

Diagonalizable Case:

$$m_{\phi_t} = m_{\phi}^t = S\Lambda^t S^{-1} = S \begin{pmatrix} \lambda_1^t & 0 & 0 \\ 0 & \lambda_2^t & 0 \\ 0 & 0 & \lambda_3^t \end{pmatrix} S^{-1}.$$

## Showing $\phi_{t+s} = \phi_{t+s}$

Diagonalizable Case:

$$m_{\phi_t} = m_{\phi}^t = S\Lambda^t S^{-1} = S \begin{pmatrix} \lambda_1^t & 0 & 0 \\ 0 & \lambda_2^t & 0 \\ 0 & 0 & \lambda_3^t \end{pmatrix} S^{-1}.$$

We then have for  $s, t \geq 0$ ,

$$m_{\phi_t} m_{\phi_s} = S\Lambda^t S^{-1} S\Lambda^s S^{-1} = S\Lambda^{t+s} S^{-1} = m_{\phi_{t+s}}$$

## The Case of a $3 \times 3$ Jordan Block

$$\Lambda = \begin{pmatrix} 1 & \lambda & 0 \\ 0 & 1 & \lambda \\ 0 & 0 & 1 \end{pmatrix}$$

## The Case of a $3 \times 3$ Jordan Block

$$\Lambda = \begin{pmatrix} 1 & \lambda & 0 \\ 0 & 1 & \lambda \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \Lambda^n = \begin{pmatrix} 1 & \lambda n & \frac{\lambda^2 n(n-1)}{2} \\ 0 & 1 & \lambda n \\ 0 & 0 & 1 \end{pmatrix}.$$



## The Case of a $3 \times 3$ Jordan Block

$$\Lambda = \begin{pmatrix} 1 & \lambda & 0 \\ 0 & 1 & \lambda \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \Lambda^n = \begin{pmatrix} 1 & \lambda n & \frac{\lambda^2 n(n-1)}{2} \\ 0 & 1 & \lambda n \\ 0 & 0 & 1 \end{pmatrix}.$$

Exercise:  $\Lambda^t \Lambda^s = \Lambda^{t+s}$ .

## Example

$$\phi(z) = \left( \frac{z_1 + 2z_2 + 1}{-z_1 + 2z_2 + 3}, \frac{-2z_1 + 2z_2 + 2}{-z_1 + 2z_2 + 3} \right)$$

## Example

### Example

$$\begin{aligned}\phi(z) &= \left( \frac{z_1 + 2z_2 + 1}{-z_1 + 2z_2 + 3}, \frac{-2z_1 + 2z_2 + 2}{-z_1 + 2z_2 + 3} \right) \\ &= \frac{\begin{pmatrix} 1 & 2 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}}{(-1, 2)^T (z_1, z_2) + 3} = \frac{Az + B}{\langle z, C \rangle + D}.\end{aligned}$$

## Example

### Example

$$\begin{aligned}\phi(z) &= \left( \frac{z_1 + 2z_2 + 1}{-z_1 + 2z_2 + 3}, \frac{-2z_1 + 2z_2 + 2}{-z_1 + 2z_2 + 3} \right) \\ &= \frac{\begin{pmatrix} 1 & 2 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}}{(-1, 2)^T (z_1, z_2) + 3} = \frac{Az + B}{\langle z, C \rangle + D}.\end{aligned}$$

Thus the associated matrix  $m_\phi$  is given by

$$\begin{pmatrix} A & B \\ C^* & D \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 \\ -2 & 2 & 2 \\ -1 & 2 & 3 \end{pmatrix}$$

## Example

### Example

$$\begin{aligned}\phi(z) &= \left( \frac{z_1 + 2z_2 + 1}{-z_1 + 2z_2 + 3}, \frac{-2z_1 + 2z_2 + 2}{-z_1 + 2z_2 + 3} \right) \\ &= \frac{\begin{pmatrix} 1 & 2 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}}{(-1, 2)^T (z_1, z_2) + 3} = \frac{Az + B}{\langle z, C \rangle + D}.\end{aligned}$$

Thus the associated matrix  $m_\phi$  is given by

$$\begin{pmatrix} A & B \\ C^* & D \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 \\ -2 & 2 & 2 \\ -1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -\frac{1}{4} \\ 0 & \frac{1}{2} & -\frac{1}{8} \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ -1 & 2 & 1 \\ -4 & 0 & 4 \end{pmatrix}$$

## Example Continued

### Example

$$\begin{aligned} m_{\phi_t} &= \begin{pmatrix} 1 & 0 & -\frac{1}{4} \\ 0 & \frac{1}{2} & -\frac{1}{8} \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & \frac{t}{2} & \frac{t(t-1)}{8} \\ 0 & 1 & \frac{t}{2} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ -1 & 2 & 1 \\ -4 & 0 & 4 \end{pmatrix} \\ &= \begin{pmatrix} \frac{2-t^2}{2} & t & \frac{t^2}{2} \\ -t & 1 & t \\ -\frac{t^2}{2} & t & \frac{t^2+2}{2} \end{pmatrix} \end{aligned}$$

## Example Continued

### Example

$$\begin{aligned} m_{\phi_t} &= \begin{pmatrix} 1 & 0 & -\frac{1}{4} \\ 0 & \frac{1}{2} & -\frac{1}{8} \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & \frac{t}{2} & \frac{t(t-1)}{8} \\ 0 & 1 & \frac{t}{2} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ -1 & 2 & 1 \\ -4 & 0 & 4 \end{pmatrix} \\ &= \begin{pmatrix} \frac{2-t^2}{2} & t & \frac{t^2}{2} \\ -t & 1 & t \\ -\frac{t^2}{2} & t & \frac{t^2+2}{2} \end{pmatrix} \end{aligned}$$

$$\phi_t(z_1, z_2) = \left( \frac{(2-t^2)z_1 + 2tz_2 + t^2}{-t^2z_1 + 2tz_2 + t^2 + 2}, \frac{-2tz_1 + 2z_2 + 2t}{-t^2z_1 + 2tz_2 + t^2 + 2} \right).$$

## Example Continued

### Example

$$\begin{aligned} m_{\phi_t} &= \begin{pmatrix} 1 & 0 & -\frac{1}{4} \\ 0 & \frac{1}{2} & -\frac{1}{8} \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & \frac{t}{2} & \frac{t(t-1)}{8} \\ 0 & 1 & \frac{t}{2} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ -1 & 2 & 1 \\ -4 & 0 & 4 \end{pmatrix} \\ &= \begin{pmatrix} \frac{2-t^2}{2} & t & \frac{t^2}{2} \\ -t & 1 & t \\ -\frac{t^2}{2} & t & \frac{t^2+2}{2} \end{pmatrix} \end{aligned}$$

$$\phi_t(z_1, z_2) = \left( \frac{(2-t^2)z_1 + 2tz_2 + t^2}{-t^2z_1 + 2tz_2 + t^2 + 2}, \frac{-2tz_1 + 2z_2 + 2t}{-t^2z_1 + 2tz_2 + t^2 + 2} \right).$$

It is a straightforward calculation to see that  $\phi_0 = I$  and  $\phi_1 = \phi$ .



## Nonrational Example

Let  $\phi(z) = (\phi_1(z_1, z_2), \phi_2(z_1, z_2))$  where

## Nonrational Example

Let  $\phi(z) = (\phi_1(z_1, z_2), \phi_2(z_1, z_2))$  where

$$\phi_1(z) = \frac{15z_1 + z_2 + 1 + 4\sqrt{2z_2(z_1 + 1)} + 4\sqrt{2(1 - z_1^2)} + 2\sqrt{z_2(1 - z_1)}}{-z_1 + z_2 + 17 + 4\sqrt{2z_2(z_1 + 1)} + 4\sqrt{2(1 - z_1^2)} + 2\sqrt{z_2(1 - z_1)}}$$

$$\phi_2(z) = \frac{16z_2 - z_1 + 1 + 8\sqrt{z_2(1 - z_1)}}{-z_1 + z_2 + 17 + 4\sqrt{2z_2(z_1 + 1)} + 4\sqrt{2(1 - z_1^2)} + 2\sqrt{z_2(1 - z_1)}}.$$

## Nonrational Example II

Define the following:

$$A := 1024z_1 + 64t^2z_2 + t^2(t+7)^2(1-z_1) + 256t\sqrt{2z_2(z_1+1)}$$

$$+ 32t(t+7)\sqrt{2(1-z_1^2)} + 16t^2(t+7)\sqrt{z_2(1-z_1)}$$

$$B := 1024 + 64t^2z_2 + t^2(t+7)^2(1-z_1) + 256t\sqrt{2z_2(z_1+1)}$$

$$+ 32t(t+7)\sqrt{2(1-z_1^2)} + 16t^2(t+7)\sqrt{z_2(1-z_1)}$$

$$C := 64t^2(1-z_1) + 1024z_2 + 512t\sqrt{z_2(1-z_1)}$$

$$D := 1024 + 64t^2z_2 + t^2(t+7)^2(1-z_1) + 256t\sqrt{2z_2(z_1+1)}$$

$$+ 32t(t+7)\sqrt{2(1-z_1^2)} + 16t^2(t+7)\sqrt{z_2(1-z_1)}.$$

## Constructing the Semigroup

A calculation shows  $\phi_t(z) = (\phi_{1_t}(z), \phi_{2_t}(z))$  where  $\phi_{1_t}(z)$  and  $\phi_{2_t}(z)$  are given by

$$\phi_{1_t}(z) = \frac{A}{B}$$

and

$$\phi_{2_t}(z) = \frac{C}{D}$$

## Constructing the Semigroup

A calculation shows  $\phi_t(z) = (\phi_{1_t}(z), \phi_{2_t}(z))$  where  $\phi_{1_t}(z)$  and  $\phi_{2_t}(z)$  are given by

$$\phi_{1_t}(z) = \frac{A}{B}$$

and

$$\phi_{2_t}(z) = \frac{C}{D}$$






A calculation shows that this is a one-parameter semigroup for  $\phi : \mathbb{B}_2 \rightarrow \mathbb{B}_2$ .

Thank You!

Thank You!

Questions?

# References

-  M. Abate. *Iteration Theory of Holomorphic Maps on Taut Manifolds*,  
**Mediterranean Press, Rende, Cosenza, 1989.**
-  E. Berkson and H. Porta. *Semigroups of Analytic Functions and Composition Operators*,  
**Michigan Math. J. 25 (1978) 111–115.**
-  F. Bracci, M. Contreras, S. Díaz-Madrigal. *Classification of Semigroups of Linear Fractional Maps in the Unit Ball*,  
**Adv. Math., 208, 1 (2007) 318-350.**
-  C. Cowen, D. Crosby, T. Horne, R. Ortiz Albino, A. Richman, Y. Yeow, B. Zerbe. *Geometric Properties of Linear Fractional Maps*.  
**Indiana University Mathematics Journal, Vol. 55m No. 2, pp.553-577 (2006).**
-  C. Cowen. *Iteration and the Solution of Functional Equations for Functions Analytic in the Unit Disk*  
**Trans. Amer. Math. Soc. 265, No. 1 (1981) 69-95.**



# References



C. Cowen and B. MacCluer, *Linear Fractional Maps of the Ball and Their Composition Operators*,  
**Acta Sci. Math (szeged)**, **66 (2000)**, 351-376.



K. Engel and R. Nagel. *One-Parameter Semigroups for Linear Evolution Equations*,  
**Graduate Texts in Mathematics**, Springer-Verlag New York, 194 (2000).



C. de Fabritiis *On the Linearization of a Class of Semigroups on the Unit Ball of  $\mathbb{C}^n$* ,  
**Ann. Mat. Pura Appl. (IV)** **166 (1994)** 363–379.



B. MacCluer. *Iterates of holomorphic self-maps of the unit ball in  $\mathbb{C}^N$*  ,  
**Michigan Mat. J.** **30, no. 1 (1983)**, 97-106.